Model Counting for Logical Theories Tuesday

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Tuesdaycomputational complexity, probability theoryWednesdayrandomized algorithms, Monte Carlo methodsThursdayhashing-based approach to model countingFridayfrom discrete to continuous model counting

Outline

1. Complexity theory: $\mathbf{P},~\mathbf{NP},~\text{and}~\#\mathbf{P}$

2. Probability theory

Probability theory: Events Probability theory: Random variables

Decision problems and algorithms

Decision problem: $L \subseteq \{0,1\}^*$ (encodings of yes-instances)

Algorithm for L: says "yes" on every $x \in L$, "no" on every $x \in \{0,1\}^* \setminus L$

Time complexity

- of algorithm \mathcal{A} on input x
- of algorithm \mathcal{A} on inputs of length n (worst-case)
- ▶ of decision problem L

Complexity class ${\bf P}$ and efficient algorithms

Cobham–Edmonds thesis:

Efficiently computable in a reasonable computational model = Computable in polynomial time on a Turing machine

$$\mathbf{P} = \bigcup_{d \ge 1} \bigcup_{c \ge 1} \mathrm{DTIME}(c \cdot n^d)$$

Problems with efficiently verifiable solutions: ${\bf NP}$

- Definition via certificates
- Definition via nondeterministic machines

Reductions and $\operatorname{\mathbf{NP}-complete}$ problems

- Polynomial-time reduction
- NP-hard and NP-complete problems

From decision to counting problems

Real-valued problem: $f: \{0,1\}^* \to \mathbb{R}$ Counting problem: $f: \{0,1\}^* \to \{0,1,2,\ldots\}$

 $\#{\bf P}:$ consists of problems that count the number of certificates to instances of ${\bf NP}\text{-}{\sf problems}$

Complexity classes: brief summary

 \mathbf{P} : polynomial time (efficiently solvable)

 ${\bf NP}:$ nondeterministic polynomial time (with efficiently verifiable solutions)

 $\#\mathbf{P}:$ counting polynomial time

1. Complexity theory: $\mathbf{P},\,\mathbf{NP},\,\text{and}\,\,\#\mathbf{P}$

2. Probability theory Probability theory: Events Probability theory: Random variables Recap: Measured theories

Measured theories and model count

A logical theory \mathcal{T} is measured if every $\llbracket \varphi \rrbracket$ is measurable. The model count of a formula φ is $mc(\varphi) = \mu(\llbracket \varphi \rrbracket)$.

σ -algebras

 σ -algebra (D, \mathcal{F}) : domain D, set of subsets $\mathcal{F} \subseteq 2^D$ such that

 $\begin{array}{ccc} \varnothing \in \mathcal{F} & \text{(the empty set is an element)} \\ A \in \mathcal{F} & \Longrightarrow & D \setminus A \in \mathcal{F} & \text{(closure under complementation)} \\ A_i \in \mathcal{F} & \Longrightarrow & \bigcup_i A_i \in \mathcal{F} & \text{(closure under countable union)} \end{array}$

Examples

- finite set D, $\mathcal{F} = 2^D$
- D = ℝ, F obtained from the set of all open intervals by adding all complements and countable unions iteratively until the closure properties are met (Borel hierarchy)

Measure: How big is a set?

Measure μ for $(D,\mathcal{F}):$ maps each $A\in\mathcal{F}$ to a real number $\mu(A)\geq 0$

More formally

$$\begin{array}{ll} A \in \mathcal{F} & \Longrightarrow & \mu(A) \geq \mu(\varnothing) = 0 \\ A_i \in \mathcal{F} \text{ disjoint } & \Longrightarrow & \mu(\bigcup_i A_i) = \sum_i \mu(A_i) \end{array}$$

Measure space (D, \mathcal{F}, μ) : σ -algebra (D, \mathcal{F}) , measure $\mu : \mathcal{F} \to \mathbb{R}$

Probability theory: Events

Probability spaces

Definition

A triple $(\Omega, \mathcal{F}, \mathsf{P})$ is a **probability space** if \mathcal{F} is a σ -algebra of subsets of Ω and P is a measure on (Ω, \mathcal{F}) that satisfies $\mathsf{P}(\Omega) = 1$.

Probability spaces

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►
$$\mathsf{P}(A) \ge 0$$
 for all $A \in \mathcal{F}$.
► $\mathsf{P}\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mathsf{P}(A_i)$ if $A_i \cap A_j = \emptyset$ for $i \ne j$.
► $\mathsf{P}(\Omega) = 1$.

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▶ $\mathsf{P}(\Omega) = 1$.

Discrete probability space: Ω is finite.

For such spaces it's usually convenient to pick $\mathcal{F} = 2^{\Omega}$.

Law of Sum

If events A and B are disjoint $(A \cap B = \emptyset)$, then $P(A \cup B) = P(A) + P(B)$.

If A_1, \ldots, A_n are pairwise disjoint events $(A_i \cap A_j = \emptyset \text{ for all } i \neq j),$ then $\mathsf{P}(A_1 \cup \ldots \cup A_n) = \sum_{i=1}^n \mathsf{P}(A_i).$

Probability of Union

Is it true that $P(A \cup B) = P(A) + P(B)$?

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Is it true that
$$P(A \cup B) = P(A) + P(B)$$
?

Answer:

This is only true if $P(A \cap B) = 0$.

Example

A fair die gives each $k \in \{1, 2, 3, 4, 5, 6\}$ with probability 1/6. Consider $A = \{1, 2, 3\}$ and $B = \{2, 4, 6\}$. P[outcome ≤ 3] = P[A] = 1/2. P[outcome even] = P[B] = 1/2. P[outcome ≤ 3 or even] = P[$A \cup B$] = P[$\{1, 2, 3, 4, 6\}$] = 5/6 \neq 1/2 + 1/2.

Probability of Union

Is it true that
$$P(A \cup B) = P(A) + P(B)$$
?

Answer: This is only true if $P(A \cap B) = 0$.

In general,

$$\mathsf{P}(A\cup B)=\mathsf{P}(A)+\mathsf{P}(B)-\mathsf{P}(A\cap B).$$

Why?

$$\begin{split} \mathsf{P}(A \cup B) &= \mathsf{P}(A) + \mathsf{P}(\overline{A} \cap B) \\ \mathsf{P}(B) &= \mathsf{P}(\overline{A} \cap B) + \mathsf{P}(A \cap B) \\ \mathsf{P}(A \cup B) - \mathsf{P}(B) &= \mathsf{P}(A) - \mathsf{P}(A \cap B) \end{split}$$

The Union Bound

We know that

$$\mathsf{P}(A \cup B) = \mathsf{P}(A) + \mathsf{P}(B) - \mathsf{P}(A \cap B).$$

Observe that, as a corollary,

$$\mathsf{P}(A \cup B) \le \mathsf{P}(A) + \mathsf{P}(B).$$

Generalize this:

$$\mathsf{P}\left(\bigcup_{i=1}^{n} A_{i}\right) = \sum_{i=1}^{n} \mathsf{P}(A_{i}) - \sum_{1 \leq i_{1} < i_{2} \leq n} \mathsf{P}(A_{i_{1}}A_{i_{2}}) + \dots + (-1)^{n+1} \mathsf{P}(A_{1} \dots A_{n})$$
(difficult)
$$\mathsf{P}\left(\bigcup_{i=1}^{n} A_{i}\right) \leq \sum_{i=1}^{n} \mathsf{P}(A_{i})$$
(easy; union bound)

Law of Complement

$$\mathsf{P}(\overline{A}) = 1 - \mathsf{P}(A).$$

What about Product?

Does the equality $P(A \cap B) = P(A) \cdot P(B)$ hold?

Does the equality $P(A \cap B) = P(A) \cdot P(B)$ hold?

The answer is NO (in the general case). (Although it does hold in an important special case, to be discussed later.)

Conditional probability of A given B(probability that event A occurs given that event B occurs) is defined as

$$\mathsf{P}(A \mid B) = \frac{\mathsf{P}(A \cap B)}{\mathsf{P}(B)}$$

if $\mathsf{P}(B) > 0$ (and undefined otherwise).

Example

A fair die gives each $k \in \{1, 2, 3, 4, 5, 6\}$ with probability 1/6. P[outcome $\leq 5 \mid$ outcome even] = ?

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Conditional probability is probability!

If $\mathsf{P}(B)>0,$ then the function $\mathsf{Q}\colon 2^\Omega\to [0,1]$ defined by

$$\mathsf{Q}(A) = \mathsf{P}(A \mid B)$$

- is a probability measure.
 - What does this mean?

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 - So what?

$$\mathsf{P}(A \cup C \mid B) = \mathsf{P}(A \mid B) + \mathsf{P}(C \mid B) - \mathsf{P}(A \cap C \mid B)$$
$$\mathsf{P}\left(\bigcup_{i=1}^{n} A_i \mid B\right) \le \sum_{i=1}^{n} \mathsf{P}(A_i \mid B)$$

. . .

Law of Total Probability

Let B_1, \ldots, B_m be a **partition**: $\mathsf{P}(B_i \cap B_j) = 0$ for $i \neq j$ and $\mathsf{P}(B_1 \cup \ldots \cup B_m) = 1$.

Suppose $P(B_i) > 0$ for all *i*.

Then for any event A

$$\mathsf{P}(A) = \sum_{i=1}^{m} \mathsf{P}(A \mid B_i) \cdot \mathsf{P}(B_i).$$

Independent events: Example

Example

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A fair die gives each $k \in \{1, 2, 3, 4, 5, 6\}$ with probability 1/6. P[outcome $\leq 4 \mid$ outcome even] = ? Consider $A = \{1, 2, 3, 4\}$ and $B = \{2, 4, 6\}$. P[outcome ≤ 4] = P[A] = 2/3. P[outcome even] = P[B] = 1/2. P[outcome $\leq 4 \mid$ outcome even] = P[$A \mid B$] = = $\frac{P[outcome \leq 4 \text{ and even}]}{P[outcome even]} = \frac{P[\{2, 4\}]}{P[\{2, 4, 6\}]} = \frac{2/6}{3/6} = 2/3.$

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In this example $P[A \mid B] = P[A]$.

Independent events

 $\begin{array}{l} \mbox{When } \mathsf{P}(A \mid B) = \mathsf{P}(A)? \\ \mbox{This equality asserts that } \frac{\mathsf{P}(AB)}{\mathsf{P}(B)} = \mathsf{P}(A). \\ \mbox{Assuming } \mathsf{P}(B) > 0, \mbox{ rewrite this as } \mathsf{P}(AB) = \mathsf{P}(A) \, \mathsf{P}(B). \end{array}$

Independent events

When $P(A \mid B) = P(A)$? This equality asserts that $\frac{P(AB)}{P(B)} = P(A)$. Assuming P(B) > 0, rewrite this as P(AB) = P(A) P(B).

Definition

Events A and B are called **independent** if P(AB) = P(A) P(B).

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Events A and B are called **independent** if P(AB) = P(A) P(B).

This definition usually helps to define P.

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A fair coin is tossed twice so that the second toss does not depend on the outcome of the first.

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Model the outcome of each toss as 0 (heads) or 1 (tails).

Four possible scenarios: $\Omega = \{00, 01, 10, 11\}$. How to define P?

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Consider events $A = \{10, 11\}$ and $B = \{01, 11\}$:

"first coin lands tails" and "second coin lands tails" respectively. We want these events to have probability 1/2 each and to be independent.

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Then $P[tails, tails] = P[\{11\}] = P[A \cap B] = P[A] P[B] = 1/4.$

Three or more independent events

Events A_1, \ldots, A_n are called **independent** if for any subset $\{i_1, \ldots, i_k\} \subseteq \{1, \ldots, n\}$ $\mathsf{P}(A_{i_1} \ldots A_{i_k}) = \mathsf{P}(A_1) \ldots \mathsf{P}(A_k).$

Example

From the set of strings $\{000, 001, 002, \dots, 999\}$ a string $X_1X_2X_3$ is picked uniformly at random. Are the events $X_1 = 5$, $X_2 = 5$, and $X_3 = 5$ independent?

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What if the string 999 is excluded from the set? (homework)

Example

Consider a pyramid (a tetrahedron) with facets colored

red, blue, green, red-blue-green.

Suppose the pyramid lands on each facet with probability 1/4. Consider events R, B, G asserting that the facet the pyramid lands on has color red, blue, green on it, respectively.

Are these events independent?

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Are these events independent?

$$P(R) = P(B) = P(G) = 1/2.$$

 $P(RB) = P(RG) = P(BG) = 1/4 = (1/2)^2.$

 $\mathsf{P}(RBG) = 1/4 \neq (1/2)^3.$

These events are NOT independent, but only pairwise independent.

Probability theory: Random variables, distributions

From events to random variables

Given a probability space $(\Omega, 2^{\Omega}, \mathsf{P})$, we can talk about events $A \in 2^{\Omega}$ and their probability $\mathsf{P}(A)$. However, it is often more convenient to talk about functions of the form $X \colon \Omega \to \mathbb{R}$, which are called **random variables**.

Example:

Bernoulli trial:

 $\Omega = \{ {\rm heads, tails} \}, \, \mathsf{P}(\{ {\rm tails} \}) = p \in [0,1], \, \mathsf{P}(\{ {\rm heads} \}) = 1-p$ Define

$$X(\omega) = egin{cases} 1 & ext{if } \omega = ext{tails,} \ 0 & ext{if } \omega = ext{heads.} \end{cases}$$

We say that the random variable X has **Bernoulli distribution** with parameter p.

From events to random variables

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Example: Let $A \in 2^{\Omega}$ be an event. The **indicator function** of A is defined as

$$\mathbf{1}_{A}(\omega) = \begin{cases} 1 & \text{if } \omega \in A, \\ 0 & \text{if } \omega \notin A. \end{cases}$$

 $\mathbf{1}_{A}(\omega)$ is a random variable that has Bernoulli distribution with parameter P(A). (Why?)

From events to random variables

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Sometimes the indicator function of A is denoted by ``[A]" , e.g., ``[the coin gives heads]" .

Binomial distribution

Suppose a coin is tossed n times, the outcome of all tosses are independent, and each gives tails with probability p.

Define

$$X_i = \begin{cases} 1 & \text{if the } i \text{th toss gives tails,} \\ 0 & \text{otherwise.} \end{cases}$$

 $(X_i \text{ has Bernoulli distribution with parameter } p.)$

Define

$$X = X_1 + \ldots + X_n.$$

We say that the random variable X has **binomial distribution** with parameters n, p.

Distributions of random variables

X has **Bernoulli distribution** with parameter p:

$$\begin{array}{c|cc} x & 0 & 1 \\ \hline \mathsf{P}(X=x) & 1-p & p \end{array}$$

X has **binomial distribution** with parameters 3, p:

$$\begin{array}{|c|c|c|c|c|c|c|c|}\hline x & 0 & 1 & 2 & 3 \\ \hline \mathsf{P}(X=x) & (1-p)^3 & 3p \, (1-p)^2 & 3p^2 \, (1-p) & p^3 \\ \hline \end{array}$$

X has uniform distribution on the set $\{0, 1, 2, 3\}$:

Expectation

$$\mathsf{E}\,X = \sum_k\,k\cdot\mathsf{P}(X=k)$$

Examples

X has uniform distribution on the set $\{1,2,3,\ldots,n\}$:

x	1	2	3	 n
P(X=x)	1/n	1/n	1/n	 1/n

 $\mathsf{E} X = 1/n \cdot 1 + 1/n \cdot 2 + 1/n \cdot 3 + \ldots + 1/n \cdot n = (n+1)/2.$

Expectation

$$\mathsf{E}\,X = \sum_k\,k\cdot\mathsf{P}(X=k)$$

Examples

X has Bernoulli distribution with parameter p:

$$\begin{array}{c|cc} x & 0 & 1 \\ P(X = x) & 1 - p & p \end{array}$$

$$\begin{split} &\mathsf{E}\,X=0\cdot(1-p)+1\cdot p=p.\\ &\mathsf{E}\,X=1/2 \text{ if and only if the coin is unbiased.}\\ &\mathsf{So}\,\mathsf{E}\,X \text{ is the } \mathbf{expected} \text{ number of tails in one flip.} \end{split}$$

Expectation

$$\mathsf{E}\,X = \sum_k\,k\cdot\mathsf{P}(X=k)$$

Examples X has binomial distribution with parameters n, p:

x	0	1	2	 n
P(X=x)	$(1-p)^n$	$np(1-p)^{n-1}$	$\frac{n(n-1)}{2}p^2(1-p)^{n-2}$	 p^n

 $\mathsf{E} X = ?$

Linearity of expectation

$$\mathsf{E}\,X = \sum_k \, k \cdot \mathsf{P}(X=k)$$

$$E(X_1 + \ldots + X_n) = E X_1 + \ldots + E X_n$$
$$E(c_1 X_1 + \ldots + c_n X_n) = c_1 E X_1 + \ldots + c_n E X_n$$
(if c_i are fixed, i.e., non-random)

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(if c_i are fixed, i.e., non-random)

Example

If X has **binomial distribution** with parameters n, p:

x	0	1	2	 n
P(X=x)	$(1-p)^n$	$np(1-p)^{n-1}$	$\frac{n(n-1)}{2} p^2 (1-p)^{n-2}$	 p^n

... then X has the same distribution as $Y_1 + \ldots + Y_n$ where each Y_i has Bernoulli distribution with parameter p.

Linearity of expectation

$$\mathsf{E}\,X = \sum_k \, k \cdot \mathsf{P}(X=k)$$

$$E(X_1 + \ldots + X_n) = E X_1 + \ldots + E X_n$$
$$E(c_1 X_1 + \ldots + c_n X_n) = c_1 E X_1 + \ldots + c_n E X_n$$
(if c_i are fixed, i.e., non-random)

Example

If X has **binomial distribution** with parameters n, p:

x	0	1	2	 n
P(X=x)	$(1-p)^n$	$np(1-p)^{n-1}$	$\frac{n(n-1)}{2} p^2 (1-p)^{n-2}$	 p^n

... then X has the same distribution as $Y_1 + \ldots + Y_n$ where each Y_i has Bernoulli distribution with parameter p.

But
$$E(Y_1 + ... + Y_n) = E Y_1 + ... + E Y_n = n \cdot p$$
, so $E X = n \cdot p$.
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Properties of expectation: Summary

$$\begin{split} \mathsf{E}(\mathbf{1}_A) &= \mathsf{P}(A) & \text{for any event } A \\ \mathsf{E}(X+Y) &= \mathsf{E} X + \mathsf{E} Y \\ \mathsf{E}(cX) &= c \cdot \mathsf{E} X & \text{for any constant } c \\ \mathsf{E} c &= c & \text{for any constant } c \\ \mathsf{E} X &\geq \mathsf{E} Y & \text{if } X \geq Y \\ \mathsf{E} f(X) &= \sum_x f(x) \cdot \mathsf{P}(X=x) \\ \mathsf{If } \mathsf{E} X &= 0 \text{ and } X \geq 0, \text{ then } \mathsf{P}(X=0) = 1. \end{split}$$

Variance

$$\operatorname{Var} X = \mathsf{E}(X - \mathsf{E} X)^2 \ge 0$$

Variance

$$\operatorname{Var} X = \mathsf{E}(X - \mathsf{E} X)^2 \ge 0$$

$$Var X = E(X^{2} - 2X \cdot EX + (EX)^{2})$$

= EX^{2} - 2EX \cdot EX + (EX)^{2}
= EX^{2} - (EX)^{2}

Variance

$$\operatorname{Var} X = \mathsf{E}(X - \mathsf{E} X)^2 \ge 0$$

$$Var X = E(X^2 - 2X \cdot EX + (EX)^2)$$

= EX² - 2 EX \cdot EX + (EX)²
= EX² - (EX)²

Var X = 0 iff there exists a constant c such that P(X = c) = 1.

For all c we have ${\rm Var}(cX)=c^2\cdot {\rm Var}\, X$ and ${\rm Var}(X+c)={\rm Var}\, X.$

Variance of the sum: Example

Let X and Y be Bernoulli random variables associated to independent Bernoulli trials with parameter 1/2. Define Z = 1 - X.

$$\begin{split} \mathsf{E}(X+Y) &= \mathsf{E}\,X + \mathsf{E}\,Y = 1\\ \mathsf{E}(X+Z) &= \mathsf{E}\,X + \mathsf{E}\,Z = 1 \end{split}$$
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$$E(X + Z) = E X + E Z = 1$$

In fact, $X + Z \equiv 1$.

k	0	1	2
P(X+Y=k)	1/4	1/2	1/4
P(X+Z=k)	0	1	0

Variance of the sum: Example

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$$\mathsf{E}(X+Z) = \mathsf{E} X + \mathsf{E} Z = 1$$

In fact, $X + Z \equiv 1$.

$$\begin{array}{|c|c|c|c|c|c|c|c|} \hline k & 0 & 1 & 2 \\ \hline \mathsf{P}(X+Y=k) & 1/4 & 1/2 & 1/4 \\ \mathsf{P}(X+Z=k) & 0 & 1 & 0 \\ \hline \end{array}$$

$$Var(X + Y) = E(X + Y - 1)^{2} = 1/2$$
$$Var(X + Z) = E(X + Z - 1)^{2} = 0$$

Variance of the sum

$$\begin{aligned} \mathsf{Var}(X+Y) &= \mathsf{E} \left((X+Y) - \mathsf{E}(X+Y) \right)^2 \\ &= \mathsf{E} \left((X-\mathsf{E} X) + (Y-\mathsf{E} Y) \right)^2 \\ &= \mathsf{E} \left((X-\mathsf{E} X)^2 + 2 \left(X-\mathsf{E} X \right) (Y-\mathsf{E} Y) + (Y-\mathsf{E} Y)^2 \right) \\ &= \mathsf{E} (X-\mathsf{E} X)^2 + \mathsf{E} (Y-\mathsf{E} Y)^2 + 2 \mathsf{E} (X-\mathsf{E} X) (Y-\mathsf{E} Y) \\ &= \mathsf{Var} \, X + \mathsf{Var} \, Y + 2 \mathsf{E} (XY-X\,\mathsf{E} Y-Y\,\mathsf{E} X+\mathsf{E} X\cdot\mathsf{E} Y) \\ &= \mathsf{Var} \, X + \mathsf{Var} \, Y + 2 (\mathsf{E} XY-\mathsf{E} X\cdot\mathsf{E} Y) \end{aligned}$$

Variance of the sum

$$\begin{aligned} \mathsf{Var}(X+Y) &= \mathsf{E} \left((X+Y) - \mathsf{E}(X+Y) \right)^2 \\ &= \mathsf{E} \left((X-\mathsf{E}\,X) + (Y-\mathsf{E}\,Y) \right)^2 \\ &= \mathsf{E} \left((X-\mathsf{E}\,X)^2 + 2\,(X-\mathsf{E}\,X)(Y-\mathsf{E}\,Y) + (Y-\mathsf{E}\,Y)^2 \right) \\ &= \mathsf{E}(X-\mathsf{E}\,X)^2 + \mathsf{E}(Y-\mathsf{E}\,Y)^2 + 2\,\mathsf{E}(X-\mathsf{E}\,X)(Y-\mathsf{E}\,Y) \\ &= \mathsf{Var}\,X + \mathsf{Var}\,Y + 2\,\mathsf{E}(XY-X\,\mathsf{E}\,Y-Y\,\mathsf{E}\,X+\mathsf{E}\,X\cdot\mathsf{E}\,Y) \\ &= \mathsf{Var}\,X + \mathsf{Var}\,Y + 2(\mathsf{E}\,XY-\mathsf{E}\,X\cdot\mathsf{E}\,Y) \end{aligned}$$

The difference $E XY - E X \cdot E Y$ is called the **covariance** of X and Y, denoted Cov(X, Y).

Independence of random variables

Recall that two events A and B are called **independent** if P(AB) = P(A) P(B).

Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

In particular, if X and Y are independent, then

$$E XY = \sum_{k} k \cdot P(XY = k)$$

= $\sum_{k} k \cdot \sum_{xy=k} P(X = x, Y = y)$
= $\sum_{k} k \cdot \sum_{xy=k} P(X = x) P(Y = y)$
= $\sum_{x} x P(X = x) \sum_{y} y P(Y = y)$
= $\left(\sum_{x} x P(X = x)\right) \cdot \left(\sum_{y} y P(Y = y)\right) = E X \cdot E Y$

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Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

In particular, if \boldsymbol{X} and \boldsymbol{Y} are independent, then

 $\mathsf{E}\,XY=\mathsf{E}\,X\cdot\mathsf{E}\,Y$

Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

In particular, if X and Y are independent, then

$$\begin{split} \mathsf{E}\, XY &= \mathsf{E}\, X \cdot \mathsf{E}\, Y\\ \mathsf{Var}(X+Y) &= \mathsf{Var}\, X + \mathsf{Var}\, Y + 2(\mathsf{E}\, XY - \mathsf{E}\, X \cdot \mathsf{E}\, Y)\\ &= \mathsf{Var}\, X + \mathsf{Var}\, Y \end{split}$$

Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

In particular, if X and Y are independent, then

$$\mathsf{Var}(X+Y) = \mathsf{Var}\,X + \mathsf{Var}\,Y.$$

Two (discrete) random variables X and Y are **independent** if for any values x and y the events X = x and Y = y are independent.

In particular, if X and Y are independent, then

$$\mathsf{Var}(X+Y) = \mathsf{Var}\,X + \mathsf{Var}\,Y.$$

In general,

$$Var(X + Y) = Var X + Var Y + 2 Cov(X, Y).$$

Variance: Summary

$$Var X = \mathsf{E}(X - \mathsf{E} X)^2 \ge 0$$
$$Var X = \mathsf{E} X^2 - (\mathsf{E} X)^2$$

Var X = 0 iff there exists a constant c such that P(X = c) = 1.

For all c we have ${\rm Var}(cX)=c^2\cdot {\rm Var}\,X$ and ${\rm Var}(X+c)={\rm Var}\,X.$

$$\begin{aligned} \mathsf{Var}(X+Y) &= \mathsf{Var}\,X + \mathsf{Var}\,Y + 2\,\mathsf{Cov}(X,Y) \\ \big(\mathsf{Cov}(X,Y) &= 0 \text{ if } X \text{ and } Y \text{ are independent}\big) \end{aligned}$$

Chebyshev inequality:

$$\mathsf{P}\big(\left|X - \mathsf{E} X\right| \ge t\big) \le \frac{\mathsf{Var} \, X}{t^2}$$

Geometric distribution

Let $X_1, X_2, \ldots, X_n, \ldots$ be independent Bernoulli random variables with parameter p. Call trial i a success if $X_i = 1$ and a failure otherwise. Denote $q = 1 - p = P(X_i = 0)$.

Geometric distribution

Let $X_1, X_2, \ldots, X_n, \ldots$ be independent Bernoulli random variables with parameter p. Call trial i a success if $X_i = 1$ and a failure otherwise. Denote $q = 1 - p = P(X_i = 0)$.

Let Y denote the number of failures before the first success. Random variable Y is said to have **geometric distribution** with parameter p.

<i>y</i>	0	1	2	 n	
P(Y=y)	p	pq	pq^2	 pq^n	

Geometric distribution: Properties

y	0	1	2	 n	
P(Y=y)	p	pq	pq^2	 pq^n	

$$\mathsf{E}\,X = \frac{q}{p}$$

$$\mathsf{Var}\,X = \frac{q}{p^2}$$

Summary of today's lecture

Computational complexity:

Decision and counting problems, complexity classes $\mathbf{P},~\mathbf{NP},$ and $\#\mathbf{P}$

 Probability theory: Measures, events, random variables, probability distributions



Tuesdaycomputational complexity, probability theoryWednesdayrandomized algorithms, Monte Carlo methodsThursdayhashing-based approach to model countingFridayfrom discrete to continuous model counting