

Description Logics: a Nice Family of Logics — Relation with Other Logics —

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So far: syntax, semantics, and basics of the DL \mathcal{ALC} :

- where they come from
- **Syntax:** concepts, axioms, assertions, TBox, ABox, ontology
- **Semantics:** interpretations, models
- **Reasoning problems:** entailment, satisfiability, consistency, ... and relationships between reasoning problems

Next: relationships between

- Description Logic
- Modal Logic
- First Order Logic



A brief recap of the history of DLs

Description Logics were

- developed as logical formalisation of semantic networks in the late 1980s
- discovered to have close relationships with FOL, ML in the early 1990s
- investigated widely in the last 25+ years:
 - trade-off between expressive power and computational complexity of reasoning
 - model theory
 - ...
- used as the logical basis of the Web Ontology Language, OWL

Relationship with first-order logic (FOL)

Not hard to see:

If we view concept names A as unary predicates and roles r as binary predicates, then

- each interpretation \mathcal{I} can be seen as an FOL structure;
- each \mathcal{ALC} concept C can be translated into an FOL formula $t_x(C)$ with one free variable x such that:

$$a \in C^{\mathcal{I}} \text{ iff } \mathcal{I} \models t_x(C)[x/a]$$

Translation: see next slide



$$\begin{array}{ll}
 t_x(A) = A(x) & t_y(A) = A(y) \\
 t_x(\neg C) = \neg t_x(C) & t_y(\neg C) = \dots \\
 t_x(C \sqcap D) = t_x(C) \wedge t_x(D) & t_y(C \sqcap D) = \dots \\
 t_x(C \sqcup D) = \dots & t_y(C \sqcup D) = \dots \\
 t_x(\exists r.C) = \exists y.r(x, y) \wedge t_y(C) & t_y(\exists r.C) = \dots \\
 t_x(\forall r.C) = \dots & t_y(\forall r.C) = \dots
 \end{array}$$

Exercise 1:

- Fill in the blanks
- Why are $t_x(C)$, $t_y(C)$ formulas in one free variable?
- Translate the concept $\neg A \sqcup \exists r.\forall s.B$ into an FOL formula.



Translate an ontology $\mathcal{O} = (\mathcal{T}, \mathcal{A})$ using $t()$ as follows:

$$t(\mathcal{O}) = t(\mathcal{T}) \cup t(\mathcal{A})$$

$$t(\mathcal{T}) = \{\forall x.t_x(C) \rightarrow t_x(D) \mid C \sqsubseteq D \in \mathcal{T}\}$$

$$t(\mathcal{A}) = \{t_x(C)[x/a] \mid a: C \in \mathcal{A}\} \cup \{r(a, b) \mid (a, b): r \in \mathcal{A}\}$$

Consequence:

Theorem

- 1 a is an instance of C in \mathcal{I} iff $\mathcal{I} \models t_x(C)[x/a]$.
- 2 C is satisfiable iff $t_x(C)$ is satisfiable.
- 3 C is satisfiable w.r.t. \mathcal{O} iff $\{t_x(C)[x/a]\} \cup t(\mathcal{O})$ is satisfiable.
- 4 C is subsumed by D iff $\forall x.(t_x(C) \rightarrow t_x(D))$ is valid.
- 5 $\mathcal{O} \models C \sqsubseteq D$ iff $t(\mathcal{O}) \models \forall x.(t_x(C) \rightarrow t_x(D))$.



Observations. $t_x(C)$ uses

- only two variables
 $\Rightarrow \mathcal{ALC}$ is a fragment of the **2-variable fragment of FOL**, which is known to be decidable.
- only guarded quantification
 $\Rightarrow \mathcal{ALC}$ is a fragment of the **guarded fragment of FOL**, which is known to be decidable.



Easy case: only one role is used, e.g.:

DL concept C	\rightsquigarrow	ML formula $\varphi(C)$
$A \sqcap \exists r.(A \sqcap B)$		$A \wedge \diamond(A \wedge B)$
$A \sqcap \forall r.(A \sqcap B)$		$A \wedge \square(A \wedge B)$
$A \sqcap \exists r.A \sqcap \forall r.B$		$A \wedge \diamond A \wedge \square B$
$A \sqcap \exists r.A \sqcap \forall r.\neg A$		$A \wedge \diamond A \wedge \square \neg A$

General case: switch to **multi-modal logic (MML)**, e.g.:

$$A \sqcap \exists r.A \sqcap \forall s.(\neg A \sqcap \exists t.B) \rightsquigarrow A \wedge \langle r \rangle A \wedge [s](\neg A \wedge \langle t \rangle B)$$

MML extends the ML ...

- syntax to parameterised boxes & diamonds, and
- semantics to several accessibility relations R_s , e.g.,

$$\mathcal{M}, w \models [s]\varphi \text{ if, for all } v \in W, (w, v) \in R_s \text{ implies } \mathcal{M}, v \models \varphi$$



In ML, we are mainly concerned with a single formula.
There is no equivalent to TBoxes or ABoxes, but:

- **TBox:**

if we have the **universal modality** u , we can translate

$$C \sqsubseteq D \quad \text{into} \quad [u](\neg\varphi(C) \vee \varphi(D))$$

- **ABox:**

if we have **nominals**, we can translate

$$\begin{aligned} a : C & \text{ into } @_a(\varphi(C)) \\ (a, b) : r & \text{ into } @_a\langle r \rangle b \end{aligned}$$

Exercise 2:

Translate the TBox $\{\neg A \sqsubseteq \exists r.\forall s.B\}$ into an ML formula.



Without TBoxes, we can use the known

- algorithms for modal logic (MLAs) to **decide** satisfiability and subsumption in \mathcal{ALC}
- soundness & completeness proof of the MLA to show that \mathcal{ALC} has the
 - **finite model property:**
 C is sat. iff C is sat. in an interpretation with finite domain.
 - **tree model property:**
 C is sat. iff C is sat. in a tree-shaped interpretation.
 - **finite tree model property:**
 C is sat. iff C is sat. in a finite tree-shaped interpretation.

With TBoxes, dedicated techniques are required

to decide sat. & subsumption efficiently in practice \leadsto **over to Uli!**



References

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Chapter 4.

